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# Reformulating $R(*,m)C$ with Tree Decomposition

Shant Karakashian

*University of Nebraska - Lincoln*, shantk@cse.unl.edu

Robert J. Woodward

*University of Nebraska - Lincoln*, rwoodwar@cse.unl.edu

Berthe Y. Choueiry

*University of Nebraska - Lincoln*, choueiry@cse.unl.edu

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# Reformulating $R(*,m)C$ with Tree Decomposition

Shant Karakashian, Robert J. Woodward, Berthe Y. Choueiry

Constraint Systems Laboratory  
University of Nebraska-Lincoln

## Acknowledgements

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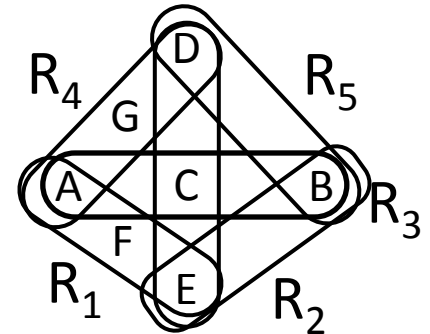
# Outline

- Introduction
- $R(*,m)C$  Property & Algorithm
- Exploit Tree Decomposition to
  - Avoid useless update & reduce propagation effort
    - ↪ Update queue:  $PROCESSQ \rightsquigarrow PROCESSMQ$
    - ↪ The two algorithms *yield the same filtering*
  - Synthesize & add new constraints to improve propagation
    - ↪ Property enforced:  $R(*,m)C \rightsquigarrow T-R(*,m,z)C$
    - ↪ The same algorithm *yields stronger filtering*
- Experimental Results
- Conclusion

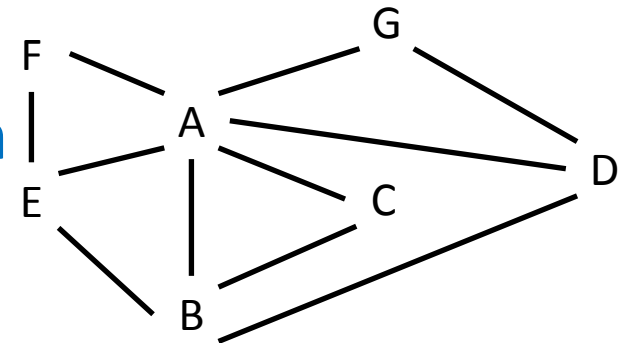
# Constraint Satisfaction Problem

- CSP
  - Variables ( $\mathcal{V}$ ), domains
  - Constraints: relations ( $\mathcal{R}$ ), scope
- Representation
  - Hypergraph
  - Primal graph
  - Dual graph
- Solved with
  - Search
  - Enforcing consistency
- Warning
  - Consistency property vs. algorithms

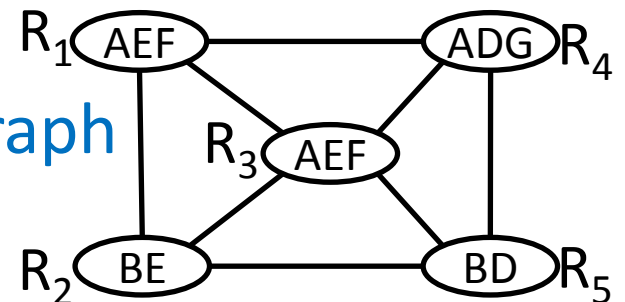
Hypergraph



Primal graph

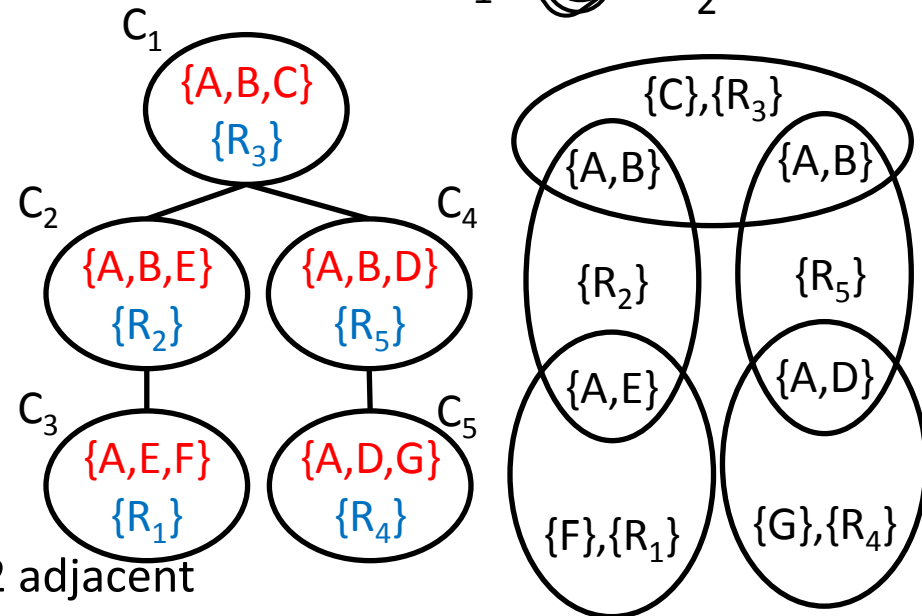
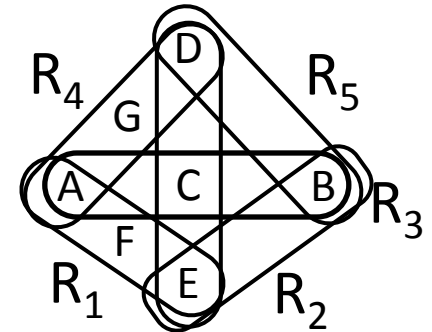


Dual graph



# Tree Decomposition

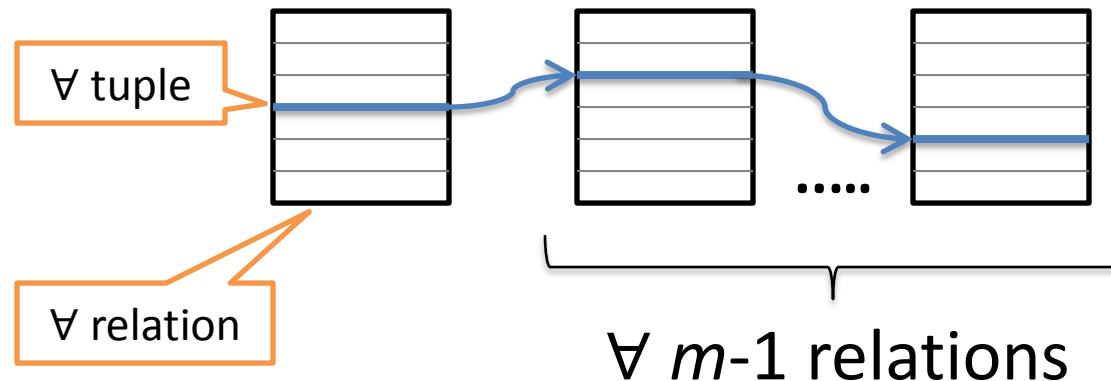
- Tree: Vertices/clusters, edges
- Each cluster is labeled with
  - A set of variables  $\subseteq \mathcal{V}$
  - A set of relations  $\subseteq \mathcal{R}$
- Two conditions
  1. For each relation  $R$ ,  $\exists$  cluster  $c_i$ 
    - $R$  appears in  $c_i$
    - $\text{Scope}(R)$  is also in  $c_i$
  2. Every variable
    - Induces a connected subtree
- Separators
  - Variables & relations common to 2 adjacent clusters
  - channel communications between clusters



# $R(*,m)C$ Property

[Karakashian+ 10]

- A CSP is  $R(*,m)C$  iff
  - Every **tuple** in a relation can be extended to the variables in the scope of any  $(m-1)$  other relations in an assignment satisfying all  $m$  relations simultaneously



# ProcessQ: Algorithm for $R(*,m)C$

- $\Phi$ : combination of  $m$  connected relations in the dual graph

$$\Phi = \{ \omega_1 = \{R_1, R_2, \dots, R_m\}, \omega_2, \omega_3, \dots, \omega_k \}$$

- Q propagation queue

$$Q = \{ \langle R_1, \omega_1 \rangle, \langle R_1, \omega_2 \rangle, \langle R_1, \omega_3 \rangle, \dots, \langle R_n, \omega_{k-1} \rangle, \langle R_n, \omega_k \rangle \}$$

- For each  $\langle R_i, \omega_j \rangle$  in Q, ProcessQ
  - Deletes from  $R_i$  tuples that cannot be extended to relations in  $\omega_j$
  - As some tuples of relations  $R_x \in \omega_j$  may lose support, it requeues  $\{ \langle R_x, \omega_y \rangle \}$  for every threatened relation

# ProcessQ: Animation

Q
$\langle R_1, \omega_1 \rangle$
$\langle R_2, \omega_1 \rangle$
$\langle R_5, \omega_1 \rangle$
$\langle R_2, \omega_2 \rangle$
$\langle R_5, \omega_2 \rangle$
$\langle R_4, \omega_2 \rangle$
$\langle R_3, \omega_3 \rangle$
$\langle R_4, \omega_3 \rangle$
$\langle R_5, \omega_3 \rangle$

Extract  $\langle R, \omega \rangle$  from Q

Define CSP  $P_\omega$

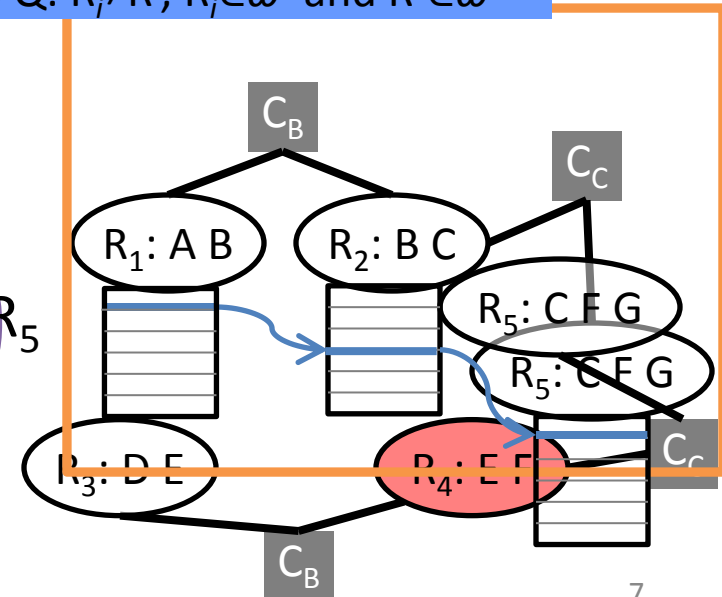
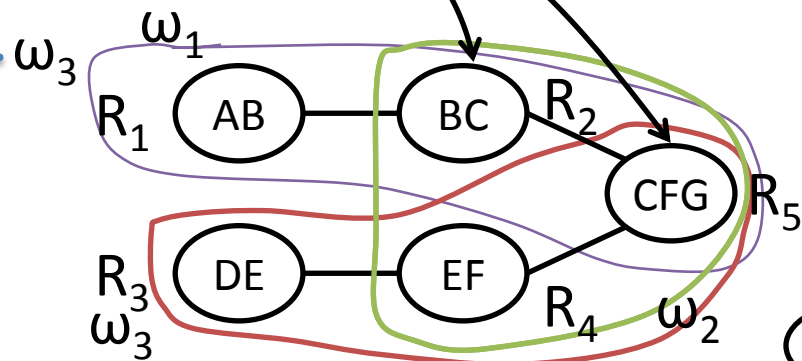
For each  $\tau$  in R

Assign  $\tau$  as a value for R

Solve  $P_\omega$  with forward checking

If no solution found: delete  $\tau$

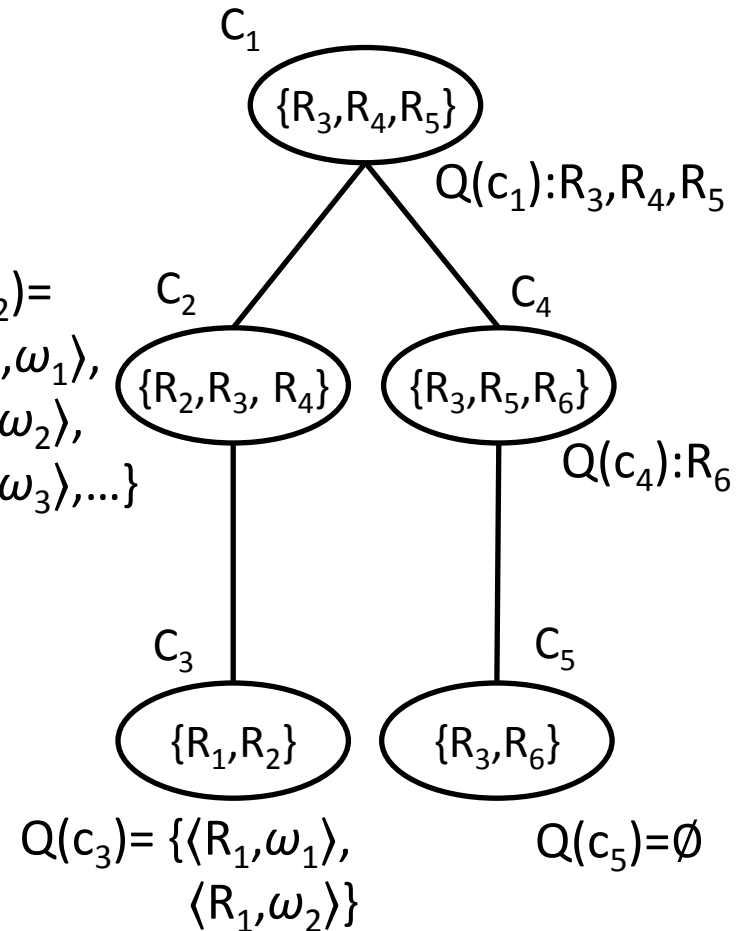
Add  $\langle R', \omega' \rangle$  to Q:  $R_i \neq R', R_i \in \omega'$  and  $R' \in \omega'$





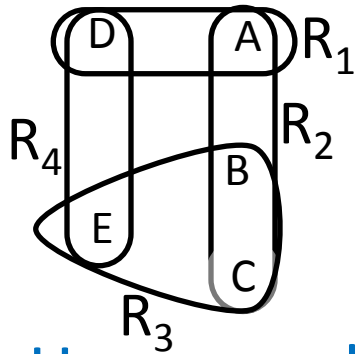
# ProcessMQ: Intelligent update scheduling

- Cluster  $c_i$  has a local queue  $Q(c_i)=\{\langle R_i, \omega \rangle\}$  for relations  $R_i$  in cluster but not in parent
- Using the tree decomposition
  - As an ordering heuristic for checking consistency of  $\langle R_i, \omega \rangle$
  - Repeat “leaves up to root, down to leaves,” until quiescence
  - Update relations in only local queue
  - Example:  $R_3$  is updated only when root is reached
- Advantage fewer updates, same filtering
  - In previous example,  $R_3$  is updated once although it appears in 3 clusters

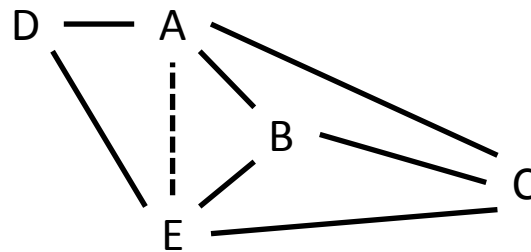


# T-R(\*,m,z)C

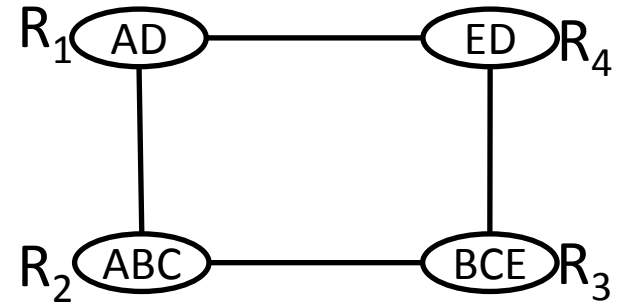
[Rollon+ 10]



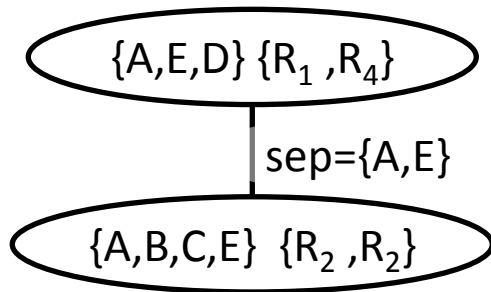
Hypergraph



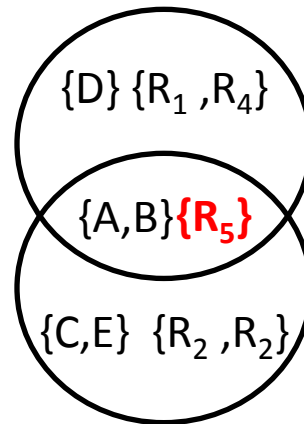
Primal graph



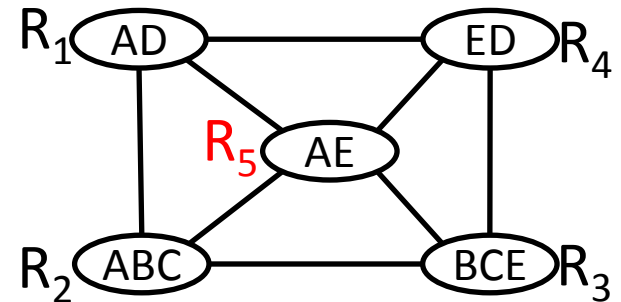
Dual graph



Tree decomposition



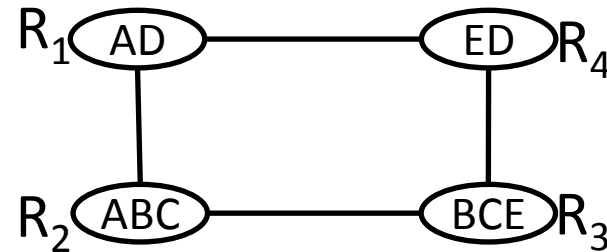
Adding  $R_5$



# T-R(\*,m,z)C Strictly Stronger than R(\*,m)C

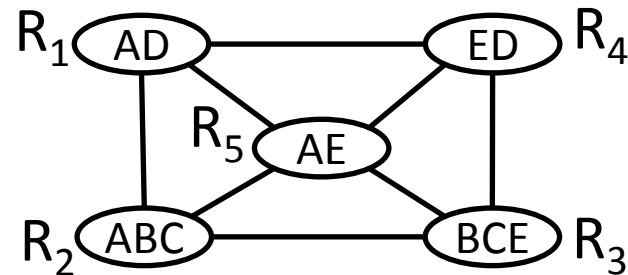
Let A, B, C, D and E be Boolean variables

$R_1$	$R_2$	$R_3$	$R_4$
A D	A B C	B C E	E D
0 0	0 0 0	0 0 0	0 0
1 1	1 1 1	1 1 1	1 1



Assignment A=0 & E=1 is valid  
Does not violate R(\*,2)C

$R_5$
A E
0 0
1 1



Assignment A=0 & E = 1 is **inconsistent**

# Experimental Results

- Experiments for finding all solutions with BTD maintaining  $wR(*, \text{best}(2,3,4))C$  and  $T\text{-}wR(*, \text{best}(2,3,4), \text{best}(5,7,9))$
- Results shown demonstrate the benefits of ProcessMQ &  $T\text{-}wR(*, m, z)C$

Benchmark	#ins	#vars	tw		ProcessQ $wR(*, \text{best})C$	ProcessMQ $wR(*, \text{best})C$	ProcessQ $T\text{-}wR(*, b, b)C$
aim-200	24	200	104.92	#C	17	17	<u>22</u>
				$t_{\text{avg}}$	246.35	252.48	<u>238.99</u>
				$t_{\text{max}}$	3,352.54	3,452.98	<u>1,540.94</u>
ogdVg	59	134	85	#C	15	15	15
				$t_{\text{avg}}$	283.27	<u>242.06</u>	266.74
				$t_{\text{max}}$	1,834.11	<u>1,508.27</u>	1,720.97
rand-3-20-20	50	20	13	#C	13	<u>14</u>	-
				$t_{\text{avg}}$	2,191.56	<u>1,949.87</u>	-
				$t_{\text{max}}$	3,481.04	<u>3,145.77</u>	-

# Conclusions

- Contributions
  - Reformulated  $R(*,m)C$  algorithm
  - New relational consistency property  $T-R(*,m,z)C$
  - Experimental analysis
- Future work
  - Study impact of choice of parameters  $z, m$
  - Develop strategies for dynamically choosing  $z, m$  as a function of the size of clusters & separators