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Invited Synthesis Paper:

Principles and practices for managing rangeland invasive plants

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Abstract

Invasive plants reduce the capacity of ecosystems to provide goods and services required by society, alter ecological processes, and can displace desirable species. They can reduce wildlife habitat quality, riparian area integrity, rangeland economic value, and enterprise net returns. The invasion process is regulated by characteristics of the invading plant and the community being invaded. The presence and spread of invasive plants is often symptomatic of underlying management problems that must be corrected before acceptable, long-term rangeland improvement can be achieved. Disturbance appears to be important early in the invasion process because it creates vacant niches that alien plants can occupy. Control of invasive plants may only open niches for establishment of other undesirable plants unless desirable plants are present to fill the vacated niches. In many instances, rangelands have deteriorated to the point that desirable species are either not present, or in such low abundance that plant community recovery is slow or will not occur without revegetation after invasive plants are controlled. Integrated weed management employs the planned, sequential use of multiple tactics (e.g. chemical, biological, cultural, and mechanical control measures) to improve ecosystem function (energy flow and nutrient cycling) and maintain invasive plant damage below economic levels, and emphasizes managing rangeland ecosystem functions to meet objectives rather than emphasizing a particular weed or control method. Sustainable, integrated invasive plant management strategies require assessing plant impacts, understanding and managing the processes influencing invasion, knowledge of invasive plant biology and ecology, and are based on ecological principles. Invasive plant management programs must be compatible with and integrated into overall rangeland resource management objectives and plans. Because of the complexity of managing invasive plants, it is imperative that relevant ecological and economic information be synthesized into user-friendly decision support systems.

Key Words: Biological control, herbicides, revegetation, native plants, alien plants, restoration, renovation, adaptive management, integrated weed management, noxious weed

Resumen

Las plantas invasoras reducen la capacidad del ecosistema para proveer los bienes y servicios requeridos por la sociedad, alteran los procesos ecológicos y pueden desplazar especies deseables. Ellas también pueden reducir la calidad del hábitat de la fauna silvestre, la integridad de las áreas ribereñas, el valor económico del pastizal y los retornos netos de la empresa. El proceso de invasión es regulado por las características de las plantas invasoras y la comunidad que esta siendo invadida. La presencia y dispersión de las plantas invasoras a menudo es un síntoma de problemas de manejo que deben ser corregidos antes de que se logren mejoras aceptables de largo plazo en el pastizal. El disturbio parece ser importante al inicio del proceso de invasión porque crea nichos vacantes que las plantas invasoras pueden ocupar. El control de plantas invasoras puede solo abrir nichos para el establecimiento de otras plantas indeseables, a menos de que estén presentes plantas deseables para llenar los nichos vacantes. En muchos casos los pastizales se han deteriorado al punto de que las especies deseables o no están presentes o están en una abundancia tan baja que la recuperación de la comunidad es lenta o no ocurrirá sin revegetación después de que las plantas invasoras han sido controladas. El manejo integrado de maleza emplea el uso secuencial planeado de tácticas múltiples (por ejemplo, medidas de control químico, biológico, cultural y mecánico) para mejorar la función del ecosistema (flujo de energía y reciclaje de nutrientes) y mantener el daño de las plantas invasoras abajo de niveles económicos, y enfatiza el manejo de la función del ecosistema de pastizal para cumplir con los objetivos en lugar de enfatizar en una maleza en particular o un método de control específico.

Las estrategias sustentables del manejo integrado de plantas invasoras requieren de evaluar los impactos de las plantas, entender y manejar el proceso que influye en la invasión, el conocimiento de la ecología y biología de la planta invasora y son basados en principios ecológicos. Los programas de manejo de plantas invasoras deben ser compatibles e integrados dentro del plan y objetivos generales de manejo de los recursos del pastizal. Debido a la complejidad del manejo de las plantas invasoras es imperativo que la información ecológica y económica relevante sea sintetizada en sistemas de soporte de toma de decisiones amigables para el usuario.

Ecological

Ecological processes may change after invading species have established and spread (Walker and Smith 1997). These changes may be minimal and the plant invader may simply increase species richness. In contrast, where ecological processes are sufficiently disrupted, native species can be displaced, increasing plant community vulnerability to further invasion and regeneration of the invasive plant. When perturbation of ecosystems exceeds ecological thresholds, ecosystem change can be so profound that controlling the invader may not restore the ecosystem to a desired condition (Hobbs and Humphries 1995). Ecosystem processes, including hydrological cycles (Graf 1978, Loope and Sanchez 1988), erosion and stream sedimentation (Lacey et al. 1989), energy flow and nutrient cycling (Versfeld and van Wilgen 1986, Vitousek and Walker 1989, Stock and Allsopp 1992), native plant regeneration (Tyser and Key 1988, Woods 1993, Belcher and Wilson 1989, Kedzie-Webb et al. 2001), and fire regimes (Hobbs and Atkins 1988, Hughes et al. 1991, Whisenant 1990, D'Antonio and Vitousek 1992) can be altered by alien plant invasions. Cheatgrass (*Bromus tectorum* L.) invasion in the Intermountain West is thought to have been facilitated by overgrazing (Young and Longland 1996) or by cheatgrass' ability to occupy vacant niches and suppress native species recruitment on areas that have not been overgrazed (Svejcar and Tausch 1991). Cheatgrass proliferation has increased the frequency and intensity of fires occurring in sagebrush grasslands (D'Antonio and Vitousek 1992). This altered fire regime has reduced the abundance of native grasses and shrubs in these grasslands and enabled cheatgrass to dominate. Invasive plants also pose a threat to species designated as threatened or endangered by reducing the quality of natural areas established to protect habitats critical to the survival of these desirable species (Randall 1997).

Invasive plants can reduce wildlife habitat quality. Areas dominated by leafy spurge (*Euphorbia esula* L.) were used less by deer and bison than non-infested areas (Trammel and Butler 1995). On native bunchgrass sites, dense spotted knapweed (*Centaurea maculosa* Lam.) populations reduced winter forage available for elk in Montana (Thompson 1996). Elk use of spotted knapweed-infested areas increased 266% after spotted knap-

Invasive plants usually have many adverse impacts as they spread through terrestrial and aquatic ecosystems. In the seminal text, *The Ecology of Invasions*, Elton (1958) described the impact of exotic or non-indigenous organisms invading new environments as "ecological explosions". Many of the estimated 5000 alien plants that now occur in natural ecosystems in the United States (Morse et al. 1995) were introduced for food, fiber, or ornamental purposes (U.S. Congress, Office of Technology Assessment 1993, Pimental et al. 2000). While many of these plants are of great value to agriculture, a small number have become invasive and threaten ecosystems.

Predicting which plants will be invasive and which ecosystems will be invaded is a highly desirable goal, but identification of salient characteristics of invasiveness and invasibility remains illusive (Crawley 1987, Mack 1989, 1996, Rejmanek and Robinson 1996, Wade 1997). Those plants that become invasive disrupt ecosystem processes and reduce the capacity of ecosystems to recover to a desirable state after disturbance and provide the goods and services (Costanza et al. 1997) demanded by society.

The presence and spread of invasive plants on rangeland is often symptomatic of underlying management problems that must be corrected before acceptable long-term progress toward control of the pests and rangeland improvement. Past rangeland management practices and climatic changes have contributed to plant community shifts by altering disturbance regimes that have accelerated invasive plant establishment and expansion (Hobbs 1989, 1991, 2000, Mack 1989, Hobbs and Huenneke 1992, Sutherst 2000).

The use of any single technology to control these species is usually not successful. Removing invasive plant species with chemical or biological control measures may only open niches for other undesirable species to occupy or to be reinvaded by the same species unless desirable species are present to fill the vacated niches. Where desirable species are either not present or in low abundance, plant community recovery will be slow or may not occur without revegetation (Masters et al. 1996, Masters and Nissen 1998).

Instead of relying on a single technology, integrated pest management emphasizes the sequential application of complementary or synergistic control measures in an economically and ecologically effective manner (Pimentel 1982). Integrated pest management is the coordinated use of

multiple tactics to assure stable ecosystem function and maintain pest damage below economic levels, while minimizing hazard to humans, animals, plants, and the environment (U.S. Congress, Office of Technology Assessment 1993). Integrated weed management emphasizes management of rangeland and pasture ecosystem function (energy flow and nutrient cycling) rather than a specific weed or control method (Scifres 1986). With this in mind, the goal of invasive plant management should be to reclaim or restore degraded weed-infested rangeland communities so that they are less susceptible to re-invasion by invasive plants and can meet land use objectives (Masters et al. 1996, Sheley et al. 1996).

Our purpose is to describe principles and practices to consider when developing integrated strategies to manage invasive plants on rangeland. Sustainable integrated invasive plant management strategies require assessing their impacts, understanding and managing the processes influencing invasion, knowledge of invasive plant biology and ecology, and integrating management tactics based on ecological principles. Ultimately, for these strategies to be successful, they must be compatible with and contribute to achieving overall rangeland ecosystem management goals and objectives.

Definitions

According to the Executive Order 13112 issued by the President of the United States on 3 February 1999, *alien species* are, with respect to a particular ecosystem, any species, including its propagules that is not native to that ecosystem. *Invasive species* are alien species whose introduction does or is likely to cause economic or environmental harm or harm to human health. *Native species* are, with respect to a particular ecosystem, a species that, other than as a result of an introduction, historically occurred or currently occurs in that ecosystem. Cronk and Fuller (1995) considered an *invasive plant* as an alien plant spreading naturally (without the direct assistance of people) in natural or seminatural habitats, which produces a significant change in terms of composition, structure or ecosystem processes. A *noxious weed* is an undesirable plant species that is regulated in some way by law (Dewey and Torell 1991, Sheley and Petroff 1999).

weed was controlled. In the Intermountain West, changes in fire frequency caused by cheatgrass invasions reduced native shrubs that are important for wildlife habitat (Miller et al. 1994).

Riparian areas are some of the most productive range sites in the West, with greater diversity of plant and wildlife species than adjoining lands (Sheley et al. 1995). In healthy riparian systems, vegetation removes sediment from water before it moves into streams. Riparian vegetation absorbs and dissipates the energy of floodwaters, thereby reducing streambank erosion. It also provides critical habitat for terrestrial and aquatic wildlife. Saltcedar (*Tamarisk* spp.), which has invaded wetlands and riparian streams throughout the western United States, reduces diversity and productivity of the herbaceous understory, and uses large quantities of water (DiTomaso 1998). Dense populations of saltcedar lower water tables, reduce surface water, decrease native vegetation needed by wildlife, and alter frequency of floods.

Economic

Economic impacts of invasive plants on rangeland have received limited attention (Naylor 2000). The difficulty quantifying the economic value of goods and services provided by ecosystems, i.e., ecological economics (see Saghoff 1995, Daly 1995), further constrains assessment of economic impacts of invasive plants. Attempts have been made to assess the impact of invasive plants on rangeland economic value and enterprise net returns. Bioeconomic models were developed to estimate direct and indirect economic impacts of leafy spurge (Leitch et al. 1996) and spotted knapweed (Hirsh and Leitch 1996). The economic impact of leafy spurge in Montana, North Dakota, South Dakota, and Wyoming is estimated at \$130 million each year (Leitch et al. 1996). Spotted knapweed costs Montana ranchers an estimated \$11 million annually (Hirsh and Leitch 1996) and if allowed to spread, cost to Montana's livestock industry could exceed \$155 million each year.

Invasion Process

Invasive plants can alter ecosystem processes and plant community successional trajectories. When describing the invasion process, it is important to consider invasion as a component of succession. Johnstone (1986) defines succession as the change in species composition over time. The rate and direction of succession

Table 1. General causes of ecological succession, contributing processes, and modifying factors (Pickett et al. 1987).

General causes	Contributing Process	Modifying factors
Site availability	Disturbance	Size, severity, time, dispersion
Species availability	Dispersal	Landscape configuration, dispersal agents
	Propagules	Land use, time since last disturbance
	Resources	Soil, topography, site history
Species performance	Ecophysiology	Germination response, assimilation rates, growth rates, genetic differentiation
	Life history	Allocation, reproductive timing, mode of reproduction
	Stress	Climate, site history, prior occupants
	Competition	Competition, herbivory, resource availability
	Allelopathy	Soil chemistry, microbes, neighboring species
	Herbivory	Climate, predators, plant defenses, patchiness

depends on the interaction of species invasion and the reaction of the species in the plant community. Succession is influenced by 3 general factors: site availability; species availability; and species performance (Table 1) (Pickett et al. 1987). These factors are affected by various processes including disturbance and plant:plant and plant:animal interactions that can be modified to alter succession. Succession can be predicted and manipulated with sufficient information about disturbance regime, site, species, and management tools.

A conceptual framework to describe plant invasion can be useful in understanding the invasion process and in making management decisions. Williamson (1996) provided a structure to organize invasion process information. He partitioned the process into 4 phases: (1) arrival and establishment; (2) spread; (3) equilibrium and effects; and (4) implications. Within each of these phases there are specific conceptual points, which further describe the invasion process. The first 3 phases represent the beginning, middle, and end of the process. The fourth phase describes the consequences of invasion on the community or ecosystem.

The invasion process begins with the arrival of alien plant propagules at the new site. Within the last 500 years, movement of alien plants has been accelerated by human-related activities, through intended or non-intended introductions (Crosby 1986, Di Castri 1989). Geographic distances and physical barriers, mountain ranges and oceans, are reduced as impediments to movement of alien species given the increased efficiency and speed with which man transports materials around the world. Mack (1989) indicated that temperate grasslands outside Eurasia have been forever changed by human activities that have facilitated the introduction of alien plants. He wrote, "Few other changes in

the distribution of the earth's biota since the end of the Pleistocene have been as radical." Many of the plants that have invaded the New World originated in the Mediterranean Basin and steppes of the Middle East (Heywood 1989). These regions have been subjected to a long history of human habitation and many plants arising from these regions co-evolved with agricultural practices. This association with agricultural production systems has enhanced development of invasive traits in plants. Introductions of alien organisms continue today despite global implementation of quarantine programs for agricultural pests (Mooney and Drake 1989).

Once the alien plant arrives at a new site, community invasion is regulated by characteristics of the invading plant and the existing community (Lawton 1986). Various, often interrelated, hypotheses about species and site invasive characteristics have been generated to provide a framework for ecological theory of invasion (Cronk and Fuller 1995). The *absence of predator hypothesis* proposes that invasive plants have an advantage because they are introduced into new environments without natural enemies from their native range. The *greater reproductive potential hypothesis* indicates that invasive plants are more fecund than native species. The *poorly adapted native species hypothesis* proposes that invasive plants exhibit a greater tolerance to resource constraints than do native species. The *chemical change hypothesis* suggests that invasive plants are better adapted to altered chemical status of an invaded site. The *balance of nature hypothesis* is centered on the concept that species-rich communities are more resistant to invasion than species-poor communities. The *empty-niche hypothesis* contends that invaded communities contain unoccupied niches ready for habitation by invasive plants. The *disturbance-produced*

gaps hypothesis suggests that some level of disturbance is necessary to allow an invading species to gain a foothold in a community. These hypotheses provide a foundation upon which to build theory and, ultimately, to predict species invasions.

Attempts to classify species according to their invasiveness have resulted in listings of genetic, physiological, and ecological attributes most often associated with successful invaders (Baker 1965, 1986, Baker and Stebbins 1965, Gray 1986, Lonsdale 1994). Mack (1996) reviewed the advantages and disadvantages of approaches to assess plants invasiveness. These approaches included: listing traits of the invasive plant; characterizing the native range of the invasive plant; developing models to predict invasiveness; quantifying growth characteristics of the invasive plant under different conditions in controlled environments; comparing characteristics of invasive and non-invasive congeners; and planting the species in the field with and without manipulation of resources. Panetta (1993) and Reichard and Hamilton (1997) suggest that the best predictor of whether or not a species would become invasive in a new environment was its invasiveness elsewhere. Nobel (1989) determined that high population numbers at any life stage in the native environment was a good indicator of invasiveness, while adult and seed longevity and plant perenniality were not reliable indicators of invasive potential. He concluded that knowledge of the invaded environment was as important as the characteristics of the invading species in predicting the invasion process.

To continue the invasion process, alien plant propagules must be dispersed into the new site and arrive at microsites that provide an environment conducive to plant establishment. The location where the immigrant plant can germinate and grow has been referred to as a "safe site" (Harper 1977), "regeneration niche" (Grubb 1977), or "invasion window" (Johnstone 1986). Safe sites meet the requirements of the alien species for germination, growth, and development and enable the plant to reach reproductive maturity.

Disturbance often increases safe site availability for invasive plant establishment (Grubb 1977, Harper 1977, Silvertown 1981, Fox 1985, Hobbs 1991). Various definitions of disturbance have been proposed (Rykiel 1985, Pickett et al. 1987, van Andel and van den Berg 1987, Petraitis et al. 1989, Hobbs and Huenneke 1992). White and Pickett (1985) defined

disturbance as any relatively discrete event in time that disrupts ecosystem, community, or population structure, and changes resources, substrate availability, or the physical environment. Events that affect resource availability and community demographic processes such as fire, storms, floods, grazing management, and fertilization are considered to be disturbances. Roads are disturbances that provide corridors for invasive plant dispersal (Lonsdale and Lane 1994, Parendes and Jones 2000) and alter the physical and chemical components of the environment (Trombulak and Frissell 2000), which further facilitate invasion. Disturbances associated with global change (global warming, increasing atmospheric CO₂, increasing nitrogen deposition, etc.) will likely influence distributions of invasive plants (Bazzaz 1990, Johnson et al. 1993, Patterson 1995, Vitousek et al. 1997, D'Antonio 2000, Dukes 2000).

Disturbance is an important factor affecting community structure and dynamics (Cooper 1926, Watt 1947, Elton 1958) that promotes invasion by alien plant species (Ewel 1986, Fox and Fox 1986, Hobbs 1989, 1991, Forcella and Harvey 1983, Pickard 1984), especially where disturbance disrupts species interactions and reduces competition (Crawley 1986, 1987, Kruger et al. 1986, Macdonald et al. 1986, Crawley 1987, Orians 1986, Fox and Fox 1986). Invasion success appears to be dependent on the extent and type of disturbance, propagule pressure (number of alien plant propagules in the community and duration of community exposure to propagules) (Rejmanek 1989), and time interval between disturbance events (Hobbs and Huenneke 1992). Community susceptibility to invasion is increased when disturbances deviate from historical patterns because the resident species are not adapted to the new disturbance regime (Burke and Grime 1996). Managing invasive plants requires manipulating the process of disturbance to favor desirable species.

Species diversity may be another factor that influences community invasibility. A commonly cited concept is that community invasibility increases as the number of species decreases (Elton 1958, Rejmanek 1989, Lodge 1993, Tilman 1996, 1997, 1999). Proposed mechanisms that support this premise are that diverse communities have a greater variety of ways to capture resources or possess species that more fully utilize resources than less diverse communities (Naeem et al. 1994, Tilman 1997); therefore, niches are already occupied when a potential invader arrives.

There is evidence that species-rich communities contain a greater number of alien species than species-poor communities (Pickard 1984, Knops et al. 1995, Robinson et al. 1995, Planty-Tabacchi et al. 1996, Palmer and Maurer 1997). Following an analysis of data collected from 184 sites, Lonsdale (1999) determined that communities richer in native species contained more alien plants than species-poor communities. There was no causal relationship between native and invasive plant diversities when measured at the community scale. Low-diversity shortgrass steppe and dry meadow communities were more resistant to invasion than high-diversity wet meadow and riparian communities (Stohlgren et al. 1998, 1999). They suggested that shortgrass steppe and dry meadow communities resist invasion because of the low levels and availability of resources (soil nutrients and water), which are essentially monopolized by the native vegetation. In contrast, high diversity communities are relatively resource rich, and resources become available following disturbance that can be exploited by invading species.

Disturbance appears to be critically important in the beginning of the invasion process because it creates openings for alien plants to occupy. Fluctuations in local species abundance in species-rich communities may provide an opening for alien plants to become established (Peart and Foin 1985). Elton (1958) indicated that the lack of invaders into a given community was the result of competitors, predators, parasites, and diseases that enabled the community to resist invasion. Invasions were successful only when these barriers were reduced or removed by disturbance, or in the case of an alien species, natural enemies were left behind in the native habitats. In contrast, Simberloff (1989) suggested that the vulnerability of a community to invasion was not because of these barriers, but rather the greater frequency of human-mediated introductions of alien species into disturbed communities. Obviously, the invasion process can be affected by a multitude of interacting factors including those described by Elton (1958) and Simberloff (1989).

Once alien species establish, the next phase is their spread through the community (Williamson 1989, Elton 1958, Okubo 1980). An important component of spread is the rate at which the invading species colonizes new sites in the community (Mooney and Drake 1989). Rate of spread is a function of both the alien species characteristics and the characteristics of the ecosystem through which the

species spreads. Moody and Mack (1988) indicated that the rate of spread of an invader will be geometric if spread is from widely spaced patches versus a linear rate if spread is from a "nascent foci" or single patch. Early in the invasion process there is a lag phase where the invasive plant populations remains small and localized for long periods before expanding exponentially (Fig. 1) (Mack 1985, Auld and Tisdell 1986, Braithwaite et al. 1989, Griffin et al. 1989, Lonsdale 1993, 1999). Hobbs and Humphries (1995) attributed this lag phase to several factors including the time needed for the invading plant to adapt to the site before spreading rapidly, the invading plant's requirement for a specific event or series of disturbance events that facilitate rapid spread, or the invading plant is simply not noticed until it becomes widespread.

Integrated Invasive Plant Management

Integrated weed management evolved from the concept of integrated pest management in agricultural crops. Integrated pest management was developed by entomologists during the late 1950s in response to problems created by excessive use of insecticides (Thill et al. 1991), and was supported by public concerns about environmental consequences of pesticide use that were catalyzed by Rachel Carson's *Silent Spring* (1962). Integrated pest management has been defined in a number of ways. Two common definitions are that this management strategy involves: (1) a combination of biological, chemical, and cultural methods for maintaining pests below economic crop injury thresholds (Burn et al. 1987, Flint and van den Bosch 1983) or (2) non-chemical pest control measures to reduce reliance on chemical pesticides (Goldstein 1978). Integrated pest management programs should be developed from interdisciplinary efforts that gather information about: (1) the ecological basis of the pest problem; (2) how to make the crop environment unfavorable for pests; (3) when pesticide treatments are needed based on pest and natural enemy populations dynamics; and (4) benefits and risks of the integrated pest management strategy for agriculture and society (Pimental 1982).

Integrated weed management emerged as a viable concept among crop weed scientists in the 1970s. Integrated weed management was defined as the application of technologies in a mutually supportive

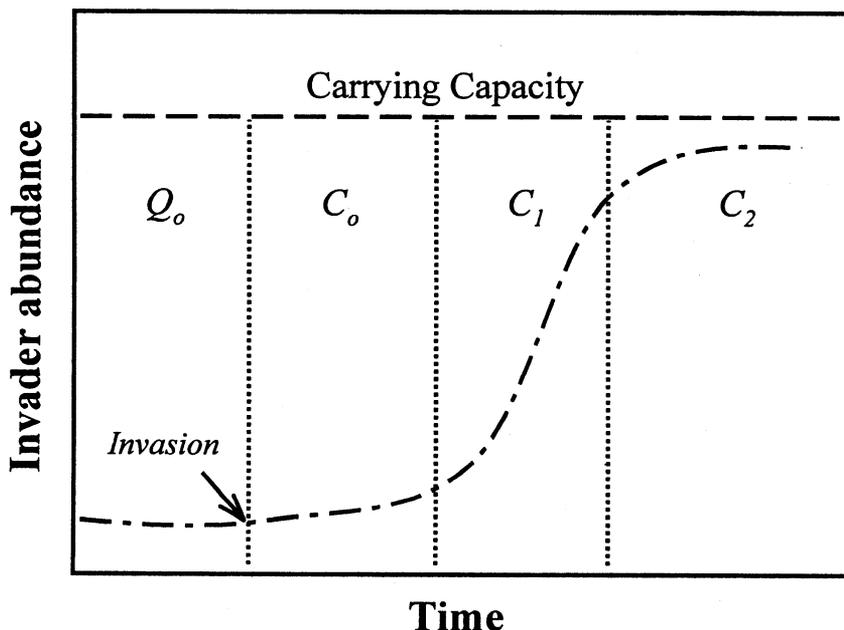


Fig. 1. Phases of weed invasion and priorities for action at each phase: Q_0 —quarantine priority phase; C_0 —eradication priority stage; C_1 —control priority phase (exponential growth phase); C_2 —maximum population level, effective control unlikely without massive resource inputs. Ease of treatment declines and difficulty and cost increases moving from left to right (Hobbs and Humphries 1995 after Chippendale 1991).

manner, and selected, integrated, and implemented with consideration of economic, ecological, and sociological consequences (Walker and Buchanan 1982). Shaw (1982) indicated that integrated weed management is an approach in which principles, practices, methods, and strategies are chosen to control pests, while minimizing undesirable results. Thill et al. (1991) defined integrated weed management as the integration of effective, environmentally safe, and sociologically acceptable control tactics that reduce weed interference below the economic injury level. Sheley et al. (1996), emphasizing management and not control of noxious rangeland weeds, indicated that integrated weed management strives to use the most economically, ecologically, and environmentally effective combination of principles, technologies, and systems to meet management goals.

Integrated weed management provides a context for managing pests that is ecosystem-centered, and not specific to a species or pest control technology. Frequently, the stated or implied goal of integrated weed management is pesticide-use reduction. We believe that this is not in keeping with the basic concept of integrated weed management, which is a sustainable approach to managing pests by combining biological, cultural, mechanical and chemical tools that minimize economic, health and

environmental risks (U.S. Congress, Office of Technology Assessment 1993). Placing value-laden judgements on the various pest management tools and ranking them according to subjective criteria should be avoided. All available tools should be considered during development of integrated weed management programs and those selected should optimize attainment of specific management objectives.

Developing effective integrated weed management programs requires a thorough understanding of the biology and ecology of the invasive plant and invaded community. Information about plant demography, propagule dynamics, seedling recruitment, plant growth and development, and methods of reproduction could help identify vulnerabilities to be exploited in integrated weed management systems (Radosevich et al. 1997). In addition, it is critical that the causes of plant invasion be understood so that they can be alleviated (Hobbs and Norton 1996).

Adapting the basic concepts of integrated weed management on cropland to integrated weed management on rangeland appears relatively straightforward. However, there are differences in management intensity and management objectives between cropland and rangeland that need to be considered. First, monocultures of agronomic species are grown on cropland and are often intentionally disturbed sever-

al times during the production cycle. Cropland is managed intensively and resource inputs, e.g., pesticides, fertilizer, and cultivation, often improve economic returns. In contrast, rangeland supports heterogeneous mixtures of plant species and is managed extensively. The relatively low value of rangeland per unit area reduces the economic viability of resource inputs compared with cropland. Second, identification of economic thresholds of injury caused by pests are central to development of integrated weed management programs in cropland. Determining economic thresholds for rangeland invasive plants is difficult and has not been adequately addressed. Furthermore, control of rangeland invasive plants designated as noxious is often mandated by law without regard to economic thresholds. Finally, impacts of invasive plants on rangeland ecosystem function and structure may be of more concern than economic impacts, especially on rangeland where other products besides livestock, e.g. wildlife, recreation, aesthetics, and water, are important.

Invasive Plant Management Strategy Components

The magnitude and complexity of rangeland weeds, combined with the costs for their control, necessitate the use of integrated weed management (Sheley et al. 1996). Education, prevention, detection, monitoring and assessment, and weed control methods are key components of integrated management strategies. Education is an under-emphasized, but important part of invasive plant management. Public awareness about the ecological, environmental, and economic impacts associated with invasive plants may help provide the political support and resources necessary for invasive plant management. Awareness also can promote activities, such as early detection of newly arriving species, in which the general public can participate. On-going educational programs provide practitioners and the general public with knowledge of current management strategies essential to sustainable invasive plant management.

Preventing invader introduction by restricting movement of propagules from infested areas can minimize invader dispersal into new habitats. Early detection followed by swift, intensive, and aggressive implementation of effective control measures during the invasion lag phase (Fig. 1) are essential to eliminate the invader, or at least to prevent seed production (Zamora et al. 1989). Once the invasion process is in the exponential phase,

eradication of the invader is usually not a realistic goal. Instead, the emphasis should be to reduce the impact of the invader to an acceptable level and keep the plant from dominating the plant community and substantively altering ecosystem processes. After the invader has reached its maximum abundance, containment of the invader or implementation of intensive restoration efforts may be the only feasible management options.

Monitoring and assessment of invasive plant distributions during invasion and in conjunction with management provides the basic information necessary for planning (Cooksey and Sheley 1997, Johnson 1999). Remote sensing tools such as aerial videography, geographic information systems, global positioning systems, and satellite-borne, narrow-band, multispectral imaging technology have the potential to improve accuracy and reduce the time needed to assess invasive plant distributions (Everitt et al. 1995, 1996a, 1996b, Bork et al. 1998). Time-repeated surveys allow continual assessment of management effectiveness and provide the information necessary to modify strategies to optimize management. Knowledge of invasive and native plant distributions is important for developing invasion risk assessment models based on invasion dynamics, environmental characteristics, and weed dispersal processes.

An adaptive management approach can complement integrated programs to manage invasive plants on rangeland. This approach requires establishing management goals, developing and implementing management programs based on the goals, monitoring and assessing impacts of management efforts, and modifying goals and invasive plant management in light of new information (Schwarz and Randall 1995, Randall 1997). Adaptive management has been developed as an integrated, multidisciplinary approach to deal with the uncertainty associated with natural resource management (Holling 1978, Walters 1986, Gunderson 1999). This approach provides a way to move from a reactive to a proactive mode of invasive plant management.

Weed Control Methods

Biological. Quimby et al. (1991) defined biological control of weeds as the planned use of living organisms to reduce the plant's reproductive capacity, density, and effect. Biological control can involve any of 3 strategies: conservation; augmentation; and importation of natural enemies (Harley and Forno 1992). Conservation involves manipulation of the environment

to enhance the effect of existing natural enemies and is usually used to manage native weeds. Augmentation employs periodic release of natural enemies and is restricted to managing weeds in high-value food crops because it requires large investments of time and money and repeated intervention. Importation, also known as *classical biological control*, is the planned relocation of natural enemies of exotic weeds from their native habitats onto weeds in their naturalized habitats. This strategy seeks to reestablish weed and natural enemy interactions that reduce the weed population to an acceptable level (DeBach and Rosen 1990). Synchrony in the life cycles of host plant and agent, adaptation of the agent to a new climate and habitats, ability of the agent to find the host at varying densities, capacity of the agent to reproduce rapidly, and the nature, extent, and timing of the damage caused by the biocontrol agent are among the factors that determine biocontrol agent effectiveness (Louda and Masters 1993).

Success of biological weed control during the past 200 years has been variable. Julien (1992) documented 610 biological control projects that involved 94 weed species in 53 countries. There have been some phenomenally successful biocontrol projects including control of *Opuntia* spp. in Australia by the moth *Cactoblastus cactorum* and control of St. Johnswort (*Hypericum perforatum* L.) in the Pacific Northwest by the beetles, *Chrysolina quadrigemina* and *C. hyperici*. There are 72 examples worldwide where weed biocontrol programs have been underway for a sufficient period to assess control. Of these programs, 28% have resulted in control that could be rated as sometimes complete (Sheppard 1992). In contrast, no control was achieved in 35% of these programs even though biological control agents were established. Important factors that have contributed to the limited success of biological weed control programs include a high level of genetic diversity in the target species, limited compatibility of agents with the invasive plant genotype, and opportunistic predation and parasitism of biocontrol agents in the introduced environment (Sheppard 1992).

The release of imported biological control agents on invasive plants is not without risk (Harris 1988, Howarth 1991, Follett and Duan 1999). By its very nature, classical biocontrol involves release of alien organisms to control other alien organisms and alter botanical composition. The consequences of natural enemy utilization of native relatives of the alien weeds are considered a potentially detri-

mental side effect of biocontrol (Harris 1988, 1990, Ehler 1990, Howarth 1991). Within a decade after release of 2 beetles, *Chrysolina quadrigemina* and *C. hyperici*, to control St. Johnswort (Huffaker and Kennett 1959), larvae of *C. quadrigemina* were found feeding on an introduced ornamental, *H. calycinum* L., and to a limited extent on a related native species, *H. concinnum* Beth (Andres 1985). The seed-head weevil, *Rhinocyllus conicus* Froel., introduced from Europe into North America to control musk thistle (*Carduus nutans* L.) (Kok and Surles 1975) has been reared from flowerheads of several native *Cirsium* species in California (Goeden and Ricker 1986, 1987, Turner et al. 1987). It has also reduced seed production of native *Cirsium* species at several locations in the central Great Plains (Louda et al. 1997). Once an insect is released into a new environment, little can be done to restrict its distribution or host affinity. Monitoring candidate biological control agents for range expansions, host shifts, and effects on related nontarget plants is critical (Howarth 1991).

Genetic variation in populations of the natural enemy and invasive plant can influence biocontrol program success (Roush 1990). High levels of genetic variability in traits that influence insect impact should increase the probability that the insect will adapt to the new environment. Furthermore, genetic variation extends the range over which the natural enemy can occur and utilize the weed (Harris and Peschken 1971). Identification of important genetic variation and its maintenance in importation, mass-rearing, and release should enhance chances of success. Biological diversity is usually highest in the center of origin of a taxon (Vavilov 1992) and the greatest genetic variation in the natural enemies may be found in the areas of weed origin (Bartlett and Van den Bosch 1964, Zwolfer et al. 1976).

Molecular biology offers tools to quantify invasive plant genetic diversity and to better match natural enemies with the target invasive plant (Nissen et al. 1995, Rowe et al. 1997). Taxonomists, evolutionary biologists and breeders use molecular techniques to measure plant genetic diversity and determine how plants are related. Selected DNA-based molecular marker techniques offer an approach to quantify invasive plant genetic diversity in native and introduced habitats and provide a better understanding of the complex relationships between invasive plants and potential biocontrol agents. This information could provide insights into the geo-

graphic origins of invasive plants and provide a means to direct the search for compatible biocontrol agents.

Chemical. Herbicides are assigned to groups according to their chemistry and mode of action (Devine et al. 1993, Ross and Lembi 1999) (Table 2). Mode of action refers to the system, process, or tissue affected by the herbicides. A herbicide is usually selective within certain rates, environmental conditions, and methods of application. Foliar-active herbicides are applied directly to the leaves or stems of plants where they are absorbed and translocated in the plant. These herbicides may or may not remain active once moved into the soil. Soil-active herbicides are absorbed by the roots from the soil water solution. Herbicides can be categorized as to whether they are applied before planting and before (preemergence) or after (postemergence) weed emergence.

Herbicides have been the dominant tools used to control invasive plants on rangeland (Bovey 1995). Potential for ground or surface water contamination, adverse effect on desirable plants, and cost of repeated application to control weeds are some of the concerns associated with herbicide use. The myriad of herbicides currently available, with different modes of action and selectivity, provide land managers with many options to control undesirable plants and manipulate plant composition (Table 2). The most commonly used herbicides on rangeland are auxin-like growth regulators (phenoxy, benzoic, or picolinic acid herbicides) that selectively control broadleaf plants and do not injure grasses when used at recommended rates.

Glyphosate¹ used on rangeland to control grass and broadleaf weeds, which has no activity in the soil. This is a postemergence herbicide that is translocated within the plant and selectivity is usually determined by the plant growth status. Control is optimized if the target plant is growing at the time of application and negated when the plant is dormant. In the Great Plains, glyphosate was applied in the fall to control cool-season grasses, such as Kentucky bluegrass (*Poa pratensis* L.) and smooth brome (*Bromus inermis* L.), but will not injure warm-season grasses that are dormant at application time (Bush et al. 1989).

The imidazolinone and sulfonyleurea herbicides: disrupt the synthesis of amino acids, leucine, isoleucine, and valine, that

are essential for plant growth and development; are phytotoxic at very low rates; and have low toxicity to vertebrates and invertebrates. Imazapic applied at 140 to 210 g ai ha⁻¹, controls leafy spurge (Masters et al. 1998, Thompson et al. 1998) and is tolerated by many species in the Gramineae, Fabaceae and Compositae families. Another unique attribute of imazapic and other imidazolinone herbicides is the ability to control many annual grass and broadleaf weed species during establishment of desirable native warm-season grasses, forbs, and legumes (Masters et al. 1996, Frye et al. 1997, Rivas-Pantoja et al. 1997, Beran et al. 1999a, 1999b, 2000). Imazapyr controls saltcedar in New Mexico when applied at 0.56 to 0.84 kg ai ha⁻¹ in late summer to early fall (Duncan and McDaniel 1998). Sulfometuron is currently registered to control cheatgrass, medusa-head [*Taeniatherum caput-medusae* (L.) Nevski], and cheat (*Bromus secalinus* L.) on non-cropland administered by state and federal land management agencies in the Intermountain West (EPA Registration No. 352-401).

Cultural. Cultural practices include fire, grazing, revegetation or reseeding, plant competition, and fertilization. These methods are generally aimed at enhancing desirable vegetation to minimize weed invasion.

Fire, along with climate and herbivory, were the primary forces responsible for the formation and maintenance of grassland ecosystems in North America (Wright and Bailey 1982). As with any disturbance, fire effects on ecosystems are influenced by its frequency, intensity, season of occurrence, and interactions with other disturbances. North American grassland fire regimes were shaped by sources of ignition, lightning and humans, and climate (Pyne 1984). Fire is a useful, if not essential, practice to meet management objectives for many plant communities in North America (Wright and Bailey 1982).

Selectivity by herbivores alters competitive interactions within plant communities (Crawley 1983, Luken 1990). In some situations sheep or goat grazing (Bowes and Thomas 1978, Landgraf et al. 1984, Walker et al. 1994, Lym et al. 1997) can control leafy spurge. Appropriate grazing by animals preferring weeds can shift the plant community toward more desired species (Walker 1994, 1995). In contrast, excessive cattle grazing without periodic rest can selectively reduce grass competitiveness, shifting the competitive advantage to weeds (Svejcar and Tausch 1991).

Revegetation with desirable plants may be the best long-term alternative for managing weeds on sites that lack suffi-

¹Refer to Table 2 for chemical names of herbicides mentioned in text.

Table 2. Selected herbicides that are currently registered for use on rangeland, pastures, or non-cropland.¹

Chemical group	Common name	Chemical name	Mode of action	Plants controlled ²	Activity ³	Application timing ⁴
Benzoic acid	Dicamba	3,6-dichloro-2-methoxybenzoic acid	Auxin-type growth regulator	B	F, S	PRE, POST
Benzonitrile	Bromoxynil	3,5-dibromo-4-hydroxybenzoxynitrile	Photosynthetic inhibitor	B	F	POST
Bipyridilium	Paraquat	1,1'-dimethyl-4,4'-bipyridinium ion	Photosystem 1 energized cell membrane disrupter	B, G	F	POST
Semicarbazones	Diflufenzopyr	2-[1-[[[(3,5-difluorophenyl)amino]carbonyl]hy-drazono]ethyl]-3-pyridine-carboxylic acid	Auxin transport inhibitor	B	F	POST
Imidazolinone	Imazethapyr	2-[4,5-dihydro-4-methyl-4-(1-methylethyl)-5-oxo-1H-imidazol-2-yl]-5-ethyl-3-pyridinecarboxylic acid	Branched-chain amino acid inhibitor	B, G	F, S	PRE, POST
	Imazapyr	2-[4,5-dihydro-4-methyl-4-(1-methylethyl)-5-oxo-1H-imidazol-2-yl]-3-pyridinecarboxylic acid	Branched-chain aminor acid inhibitor	B, G	F, S	PRE, POST
	Imazapic	2-[4,5-dihydro-4-methyl-4-(1-methylethyl)-5-oxo-1H-imidazol-2-yl]-5-methyl-3-pyridinecarboxylic acid	Branched-chain amino acid inhibitor	B, G	F, S	PRE, POST
Phenoxy acid	2,4-D	(2,4-dichlorophenoxy)acetic acid	Auxin-type growth regulator	B	F	POST
	2,4-DB	4-(2,4-dichlorophenoxy)butanoic acid	Auxin-type growth regulator	B	F	POST
	MCPA	(4-chloro-2-methylphenoxy)acetic acid	Auxin-type growth regulator	B	F	POST
Phenylurea	Diuron	N'-(3,4-dichlorophenyl)-N,N-dimethylurea	Photosynthetic inhibitor	B, G	F, S	PRE, POST
	Tebuthiuron	N-[5-(1,1-dimethylethyl)-1,3,4-thiadiazol-2-yl]-N,N'-dimethylurea	Photosynthetic inhibitor	B, G	F, S	PRE, POST
Picolinic acid	Clopyralid	3,6-dichloro-2-pyridinecarboxylic acid	Auxin-type growth regulator	B	F, S	PRE, POST
	Picloram	4-amino-3,5,6-trichloro-2-pyridine-carboxylic acid	Auxin-type growth regulator	B	F, S	PRE, POST
s-Triazine	Triclopyr	[(3,5,6-trichloro-2-pyridinyl)oxy]acetic acid	Auxin-type growth regulator	B	F, S	PRE, POST
	Atrazine	6-chloro-N-ethyl-N'-(1-methylethyl)-1,3,5-triazine-2,4-diamine	Photosynthetic inhibitor	B, G	F, S	PRE, POST
	Hexazinone	3-cyclohexyl-6-(dimethylamino)-1-methyl-1,3,5-triazine-2,4(1H,3H)-dione	Photosynthetic inhibitor	B, G	F, S	PRE, POST
	Simazine	6-chloro-N,N'-diethyl-1,3,5-triazine-2,4-diamine	Photosynthetic inhibitor	B, G	F, S	PRE, POST
Sulfonyl urea	Chlorsulfuron	2-chloro-N-[[[(4-methoxy-6-methyl-1,3,5-triazin-2-yl)amino]carbonyl]benzenesulfonamide	Branched-chain amino acid inhibitor	B, G	F, S	PRE, POST
	Metsulfuron	2-[[[[[(4-methoxy-6-methyl-1,3,5-triazin-2-yl) amino] carbonyl]amino] sulfonyl] benzoic acid	Branched-chain amino acid inhibitor	B, G	F, S	PRE, POST
	Sulfometuron	2-[[[[[(4,6-dimethyl-2-pyrimidinyl)amino] car-bonyl] amino]sulfonyl]benzoic acid	Branched-chain amino acid inhibitor	B, G	F, S	PRE, POST
Uracil	Bromacil	5-bromo-6-methyl-3-(1-methylpropyl)-2,4(1H, 3H)pyrimidinedione	Photosynthetic inhibitor	B, G	F, S	PRE, POST
Unassigned	Fosamine	ethyl hydrogen (aminocarbonyl)phosphonate	Unknown	B	F	POST
	Glyphosate	N-(phosphonomethyl)glycine	Aromatic amino acid inhibitor	B, G	F, S	POST
	Quinclorac	3,7-dichloro-8-quinolinecarboxylic acid	Cell wall formation inhibitor	B, G	F, S	PRE, POST

¹Chemical group and mode of action from Ross and Lembi (1999) and common name and chemical names from (Weed Science Society of America 1994).

²B = broadleaf species and G = grass species

³F = taken up by plant foliage and S = has activity in the soil

⁴PRE = applied before plant emerges and POST = applied after plant emerges

cient abundance of desirable species. Establishing competitive grasses, forbs, and legumes may suppress invasive plants, enhance plant community resistance to further invasion, and improve forage production and quality (Masters et al. 1996, Lym and Tober 1997, Bottoms and Whitson 1998, Ferrell et al. 1998, Masters and

Nissen 1998, Whitson and Koch 1998).

Selecting plant species is a critical consideration when developing a desired plant community if the desirable species are not present in sufficient abundance to enable regeneration within an acceptable time-frame. Jones and Johnson (1998) described an integrated approach for mak-

ing decisions about how to select plant materials for rangeland revegetation. Site potential, desired landscape, seeding objectives, conflicting land-use philosophies, appropriate plant materials, invasive plants, community seral status, and economic limitations are key components of the decision-making process.

Table 3. Examples of integrated strategies for control of invasive plants on rangeland (modified after DiTomaso 2000).

Invasive Plant	Strategy components	Citation
<i>Acroptilon repens</i> (L.) DC	Tillage, herbicide, and revegetation	Dershied et al. 1963, Bottoms and Whitson 1998, Benz et al. 1999
<i>Bromus tectorum</i> L.	Tillage, herbicide, and revegetation	Eckert and Evans 1967, Evans et al. 1967 Whitson and Koch 1998
<i>Centaurea</i> spp.	Herbicide and grazing	Whitson and Koch 1998
	Herbicide, revegetation, and biocontrol	Enloe and DiTomaso 1999
	Herbicide and revegetation	Sheley et al. 2001
<i>Cirsium arvense</i> (L.) Scop.	Burning and herbicide	Lacey et al. 1995
	Herbicide and revegetation	Wilson and Kachman 1999
<i>Euphorbia esula</i> L.	Herbicide and biocontrol	Nelson et al. 1998
	Tillage, herbicide, and revegetation	Selleck et al. 1962, Ferrell et al. 1998 Lym and Tober 1997
<i>Hypericum perforatum</i> L.	Tillage, herbicide, and fertilization	Lym and Messersmith 1993
	Grazing and herbicide	Lym et al. 1997
	Herbicide, burning, and revegetation	Masters and Nissen 1998, Masters et al. 2001
<i>Lepidium latifolium</i> L.	Tillage and revegetation	Gates and Robocker 1960
<i>Lepidium latifolium</i> L.	Mowing and herbicide	Renz and DiTomaso 1999
<i>Linaria dalmatica</i> (L.) Mill.	Tillage and revegetation	Gates and Robocker 1960
<i>Opuntia stricta</i> (Haworth) Haworth	Herbicide and biocontrol	Hoffman et al. 1998
<i>Taeniatherum caput-medusae</i> (L.) Nevski	Burning, herbicide, and revegetation	Horton 1991
	Tillage, herbicide, and revegetation	Young et al. 1969

A question faced by land managers considering revegetation is whether to use native and/or introduced plant materials (Lesica and Allendorf 1999). The value of local ecotypes (Knapp and Rice 1994, Linhart and Grant 1996), native or introduced plant cultivars with improved agronomic traits developed by formal breeding programs (Vogel et al. 1989, Vogel 2000, Casler et al. 1996), and mixed populations or hybrid genotypes (Millar and Libby 1989, Munda and Smith 1995) in revegetation programs has been detailed. Another perspective is that rather than emphasizing individual species, the focus of revegetation programs should be on establishing functional groups (Walker 1992) that maintain ecosystem processes (Noss 1991). Johnson and Mayeux (1992) argue that no special quality should be attributed to a species labeled as a "native," rather the focus should be on ecosystems as "self-sustaining systems in terms of physiognomic structure and functional processes in which various species are interchangeable."

Mechanical. Mechanical treatments involve either removal of the aerial portions of the weed or removal of enough of the root and crown to kill the plant. Annuals and some biennials and perennials can be suppressed or controlled if mowing occurs before fruits mature and viable seeds form. Mowing in the fall for 3 consecutive years decreased spotted knapweed density about 85% compared to areas that were not mowed (Rinella et al. 2001). Mowing perennial herbaceous or woody

plants that have the capability to reproduce vegetatively can actually exacerbate weed interference by stimulating production of new stems from vegetative buds below the cut surface. However, perennial plants that reproduce vegetatively can be severely damaged or killed by tillage (Derscheid et al. 1985), bulldozing, root-plowing, or grubbing (Vallentine 1989). The high cost of these mechanical treatments limits their use to control rangeland weeds.

Integrating Multiple Weed Control Strategies

There are several examples of integrated strategies used to manage invasive plants and improve rangeland communities (Table 3). Efforts to assess the compatibility of insect biocontrol agents and herbicides during development of integrated management systems are increasing (Messersmith and Adkins 1995). Revegetation has been a common component of integrated approaches because it is essential that desirable plant species, rather than another invasive plant species, fill the niche vacated by the controlled invader. Herbicides and tillage were used to suppress dalmation toadflax (*Linaria dalmatica* Mill.) and St. Johnswort (Gates and Robocker 1960), cheatgrass (Eckert and Evans et al. 1967), and medusahead (Young et al. 1969) in early attempts to prepare degraded rangeland sites for revegetation with cool-season grasses.

Approaches that include herbicide application and establishing monoculture

stands of introduced and native perennial grasses have been successfully used to suppress leafy spurge and improve forage production on rangeland. In Wyoming, seedbed preparation consisted of multiple glyphosate applications in spring and summer followed by tillage before planting introduced cool-season grasses (Ferrell et al. 1998). Introduced cool-season grasses were planted in a tilled seedbed following broadcast applications of glyphosate and 2,4-D in North Dakota (Lym and Tober 1997). The planted grasses that were most effective in suppressing leafy spurge were 'Bozoisky' Russian wildrye [*Psathyrostachys juncea* (Fisch.) Nevski] and 'Luna' pubescent wheatgrass [*Elytrigia intermedia* (Host) Beauv.] in Wyoming, and 'Rebound' smooth brome and 'Reliant' intermediate wheatgrass [*Thinopyrum intermedium* (Host) Barkw. & D.R. Dewey] in North Dakota. In Nebraska, monoculture stands of native warm-season grasses, big bluestem (*Andropogon gerardii* Vitman), indiagrass [*Sorghastrum nutans* (L.) Nash], and switchgrass (*Panicum virgatum* L.), were established on leafy spurge-infested rangeland and increased herbage yields by more than 40% and reduced leafy spurge density and yield (Masters and Nissen 1998). The sites were treated with imazapyr and sulfometuron in the fall and burned the following spring before tallgrasses were planted into the herbicide-suppressed sod without tillage.

Recent rangeland improvement research demonstrated an integrated weed manage-

ment strategy, which suppressed leafy spurge and associated vegetation and facilitated planting and establishment of stands of mixture of native warm-season grass and legume species (Masters et al. 2001). These multi-species assemblages may more fully use resources on degraded rangeland and preempt resource use by less desirable species, including leafy spurge. The strategy consisted of herbicide application, burning the herbaceous standing crop, and planting mixtures of native species without tillage. Glyphosate and imazapic were the herbicides selected to suppress existing resident vegetation, while not interfering with establishment of species in the planted mixtures. Glyphosate controlled cool-season grasses that were growing at the time of application, but provided no residual weed control. Imazapic provided residual control of leafy spurge and annual grass and broadleaf plants and was tolerated by a number of warm-season grasses (Rivas-Pantoja et al. 1997, Beran et al. 2000), forbs (Beran et al. 1999a) and legumes (Beran et al. 1999b).

Invasive Plant Management Systems as a Component of Rangeland Resource Management

To be successful, invasive plant management programs must be compatible with and integrated into overall rangeland resource management objectives and plans. Effective invasive plant management programs cannot be developed without considering other management components that impinge upon the rangeland resource. Integrating all components within the rangeland resource management program is essential because interactions among the components determine the economic and ecological sustainability of the program. For example, altering grazing management or fire regimes impact site invasibility since the invasion process can be influenced by disturbance.

What is the appropriate goal when developing rangeland resource management programs? The "desired plant community" could serve as the goal for rangeland resource management. The desired plant community concept originated with the USDI-Bureau of Land Management and was defined by the Society for Range Management, Task Group on Unity in Concepts and Terminology (1995) as, "of the several plant communities that may occupy a site, the one that has been identified through a management plan to best meet the plan's objectives for the site. It (the desired plant community) must pro-

tect the site at a minimum." This concept recognizes that plant community succession for a given site can progress along multiple trajectories and result in different outcomes. Factors that influence these outcomes include past management, plant and animal dispersal from adjacent areas, climatic conditions, disturbance regimes (past, present, and future), and species selected for revegetation projects. The desired plant community concept is consistent with prevailing state and transition (Westoby et al. 1989) and threshold (Laycock 1991, Friedel 1991) models of vegetation change. These non-equilibrium models of succession have superceded the unidirectional Clementsian climax community model (Clements 1916, Weaver and Clements 1938).

The desired plant community is an appealing concept for rangeland management because it empowers land managers to design a plant community that meets management objectives. In the context of invasive plant management, resistance to alien plant invasion would be a key criterion considered when designing a desired plant community. Obtaining the desired plant community involves managing succession, which requires knowledge of the 3 general causes of succession: site availability; differential species availability; and species performance (Table 1) (Pickett et al. 1987, Luken 1990). Within the limits of knowledge about the conditions, mechanisms, and processes controlling plant community dynamics, these 3 components can be modified to manage succession by using designed disturbance, controlled colonization, and controlled species performance (Pickett et al. 1987). Designed disturbances include activities that create or eliminate site availability and control succession such as tillage or herbicide suppression of sod. In successional management, designed disturbances are used to alter successional trajectories and to minimize continual reliance on external inputs. Controlled colonization is the intentional alteration of availability and establishment of plant species by influencing seed banks, vegetative propagule pools, and regulation of safe sites for germination and establishment of desirable species. Invasive plant seed banks can be depleted through attrition if seed production is prevented or reduced. Controlled species performance involves manipulating growth and reproduction of plant species to redirect succession. Biological and chemical weed control, grazing, mowing, fertilization, and planting competitive species can create differential species performance. Management of succession is an ongoing process moving along

a trajectory that is driven by both naturally occurring and human-induced processes. A generalized model describes the process of managing succession by using various management tools in appropriate sequences and combinations to achieve a desired grassland community structure (Fig. 2) (Masters and Nissen 1998).

The restoration ecology discipline provides goals to consider when developing and implementing strategies to manipulate community succession to meet management objectives. Restoration has been distinguished from or referred to interchangeably with rehabilitation, reclamation, reconstruction, renovation, and other terms (Whisenant 1999). The Society for Ecological Restoration (1994) defined restoration as the process of repairing damage caused by humans to the diversity and dynamics of indigenous ecosystems, and Jackson et al. (1995) provide further elaboration of the definition. Hobbs and Norton (1996) suggest a broader definition, with restoration occurring along a continuum from rebuilding totally devastated sites to maintaining pristine sites with limited management. They indicate that restoration should be applied at the landscape scale and the goal should be to return degraded ecosystems to conditions that meet conservation and production objectives in a sustainable manner.

Decision Support Systems

Invasive plant management is complex, thus all applicable information should be synthesized and presented in a way that is useful to managers. Decision support systems offer an approach to improve decision making when complex interactions are involved (Stuth and Smith 1993). Expert systems, a form of decision support systems, can improve decision making by using knowledge and experience of experts to provide users a means to assess alternative management outcomes based on specific information about the situation (Barrett and Jones 1989). Many decision support systems use heuristic ("rule of thumb") approaches to problem-solving that blend hard data with semi-structured procedures and expertise to provide information required to define a problem and possible solutions (Scifres 1987, Stuth and Smith 1993). The integrated brush management system concept developed by Scifres et al. (1983) provides a system to evaluate integrated management with multiple objectives and components. These models could be of great benefit in developing decision support systems for invasive plant management programs.

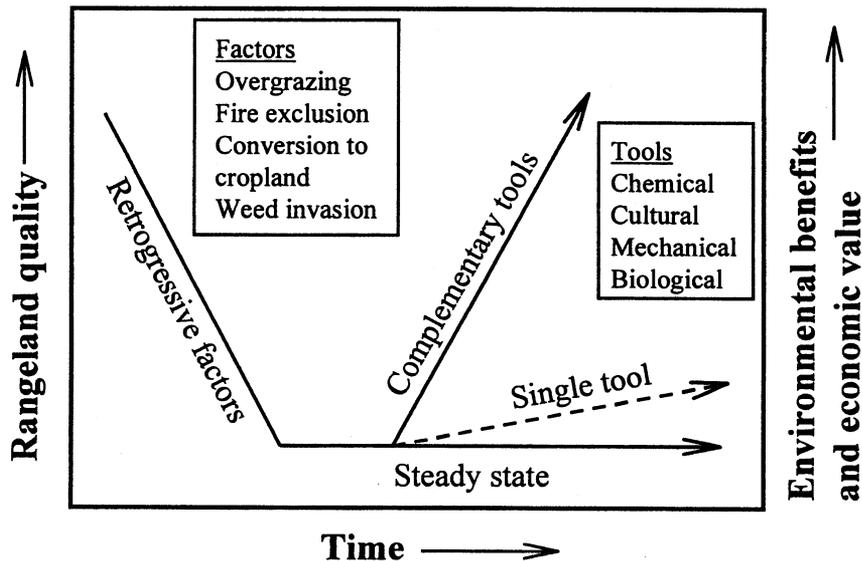


Fig. 2. Generalized community succession model for Great Plains grasslands. Retrogression leads to a steady state condition of low productivity. Reliance on a single technology results in slow grassland recovery rate. Sequential application of complementary and possibly synergistic technologies accelerates progress towards higher quality rangeland (Masters and Nissen 1998).

Conclusion

Invasive plants can have adverse effects on rangeland and pasture ecosystems by disrupting ecosystem processes and reducing their capacity to recover after disturbance. Disturbance is an important factor affecting community structure and dynamics, and facilitates alien plant invasion. Managing invasive plants requires manipulating disturbance regimes to favor desirable species. Various technologies are available for managing invasive plants, but acceptable long-term control will only be achieved when integrated weed management programs are integrated into rangeland resource management plans. Integrated weed management provides a context for managing pests that focuses on ecosystem processes and not on particular plant species or control practices. The advantages and disadvantages of weed control tools will vary according to the invasive plant and invaded site characteristics. The merits of each control measure and the potential for complementary or synergistic interactions when applying measures in appropriate sequences and combinations should be considered when developing integrated weed management programs. The reasons for the arrival, establishment, and spread of invasive plants must be understood before sustained progress can be made toward controlling the plant and improving rangeland and pasture ecosystems. Simply removing

invasive plant species with selected control measures may only open niches for other undesirable species to occupy if aggressive desirable species are not available. An appropriate goal of invasive plant management should be to restore desirable native or introduced species communities that are resistant to future invasions. Prevention, detection, and control are key components of integrated management strategies. Early detection followed by prompt implementation of effective control measures is essential to eliminate the invader. Without a commitment to taking swift action, the invasion process will progress into the exponential population expansion phase and eradication of the invader will not be a realistic goal. Invader containment or plant community restoration are the primary options once invader abundance reaches the carrying capacity of the invaded habitat. The desired plant community concept provides a useful goal for invasive plant and rangeland resource management. Ecosystem processes and successional trajectories can be manipulated to achieve the desired plant community by designing disturbance regimes and manipulating dispersal, establishment, and maintenance of desirable species. Development of decision support systems to assist managers in confronting the inherent complexity associated with managing invasive plants and rangeland ecosystems is a critical need.

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